

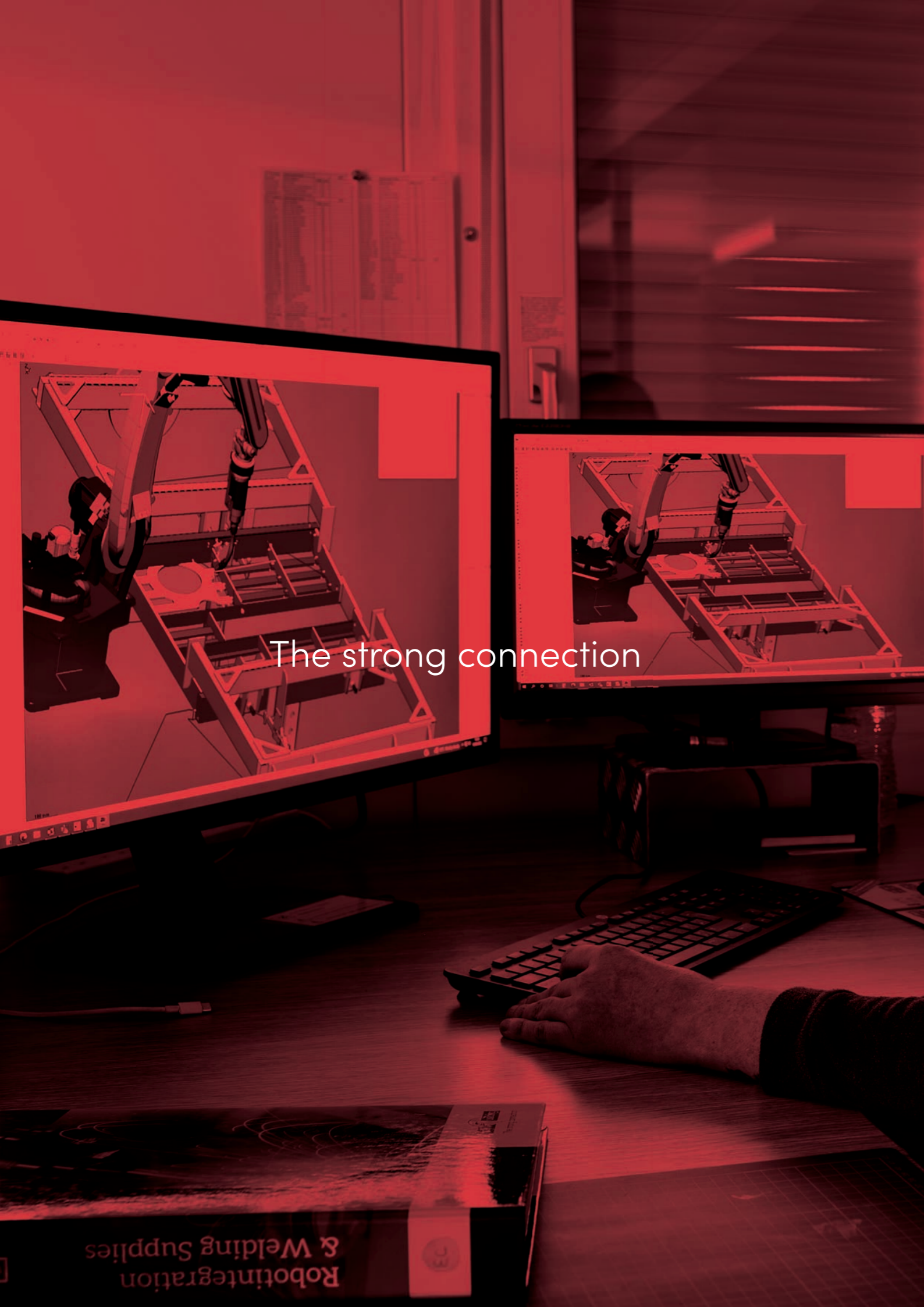
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Software solutions





The strong connection

Valk Welding softwareoplossingen

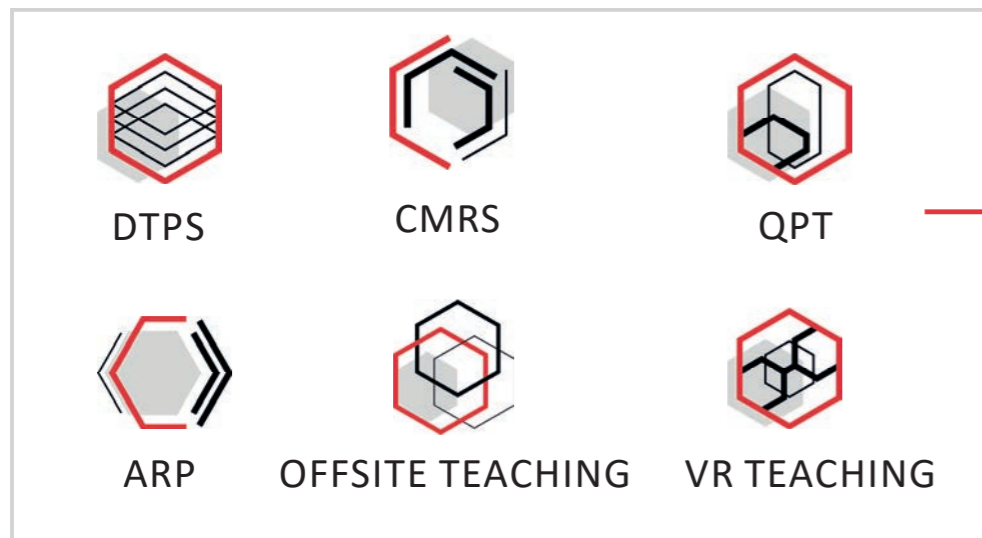
To get the maximum efficiency from your robot installation, the interaction between man and machine is particularly important. Valk Welding has developed various software solutions that provide both fast control of the robot and communication with your employees.

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From people to robot and back

The diagram to the right shows the different actions and solutions that Valk Welding can offer in terms of software.

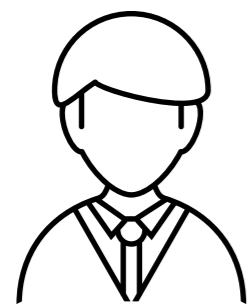
Programming the robot.



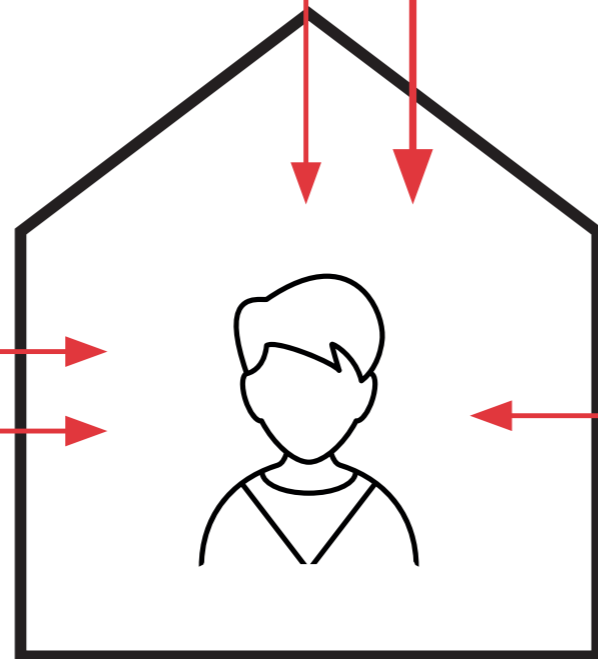
Structuring, managing and planning the production process. Additionally, internal communication about the production process is possible.



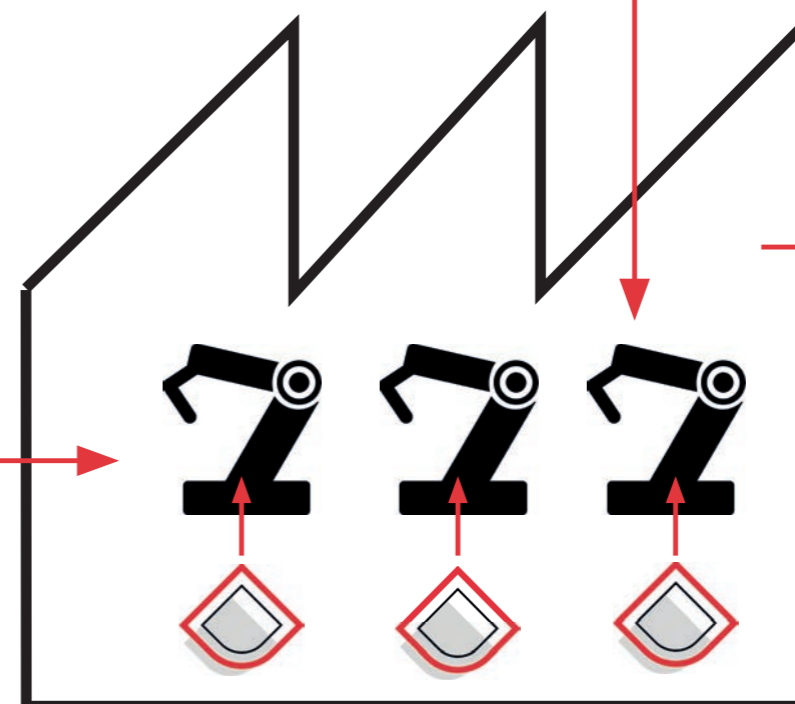
Monitoring the robot system, welding process and end product.



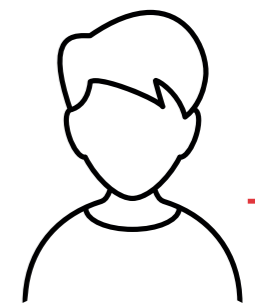
Customer



Planner



ARC-EYE



Operator



DTPS

Desktop Programming and Simulation Software

DTPS (Desktop Programming and Simulation Software) is a fully fledged 3D CAD/CAM system for programming and simulating the welding path of Panasonic arc welding robots. The offline programming software replaces programming with a teach pendant (an advanced remote control) directly on the robot. As a result, production does not have to be interrupted for programming and a maximum switch-on time of welding robot systems can be achieved. Programmers can program the most complex workpieces with the help of DTPS without having to stop the welding robot. After importing a workpiece from a CAD system, the work planner indicates the welding positions including the desired welding parameters. Because the software offers a powerful 3D simulation with collision detection, the programs can be checked down to the finest detail before they are sent to the control of the welding robot. In addition, the jigs and positioner frames can be designed and tested. DTPS forms the basis for several software programs.

DTPS facts

- DTPS offers full support for importing 2D and 3D CAD files into your virtual robotic system.
- DTPS is a powerful engineering and testing tool.
- DTPS calculates cycle times.
- Conversion of existing programs to new installations or other workstations is possible.
- Powerful 3D simulation with collision detection.
- Programs are interchangeable between the Valk Welding robot systems.
- DTPS is 100% compatible with all generations of controllers.
- Existing robot programs can easily be adapted.

How DTPS works?

System definition by Valk Welding

Because every setup is unique, it is first defined by the specialists of Valk Welding in the 3D environment before it is put into use.

Design products in 3D or import existing products from a CAD system

Within DTPS you have all the tools you need to draw every workpiece in 3D. Existing drawings from other CAD systems, with the extensions WRL, XGL, ZGL, 3DXML, STL, IGES or DXF can be imported.

Programming the robot

You can easily move the robot with the cursor, or you can click on the parts to be welded. This way you can also program the Quick Touch wire search. Welding parameters can easily be determined using the unique standard Weld Navigation function.

Checking

The program can be controlled by a full simulation of the movements and checked for collisions.

Send and start

Send programs to the robot and start production.

A few notable features:

- The internal CAD system has been expanded to include new entities and many new functions
- The installation editor with standard components has made the engineering of new systems much quicker and easier
- Programming the weld lines with automatic addition of points in free space
- Linking a powerful welding parameter database to the welding motion
- Extensive possibilities for editing programs
- All imaginable manipulations of programs for robot positions
- Extensive possibilities for file management
- Programs are interchangeable with other Valk Welding robot systems
- File transfer via Ethernet
- Export AVI files of created programs

DTPS in short

DTPS - Desktop Programming and Simulation Software is a fully fledged 3D CAD/CAM system for programming and simulating the welding path on Panasonic arc welding robots. The offline programming software replaces programming with a teach pendant directly at the robot. As a result, production does not have to be interrupted for programming and a maximum switch-on time of welding robot systems can be achieved.



QPT

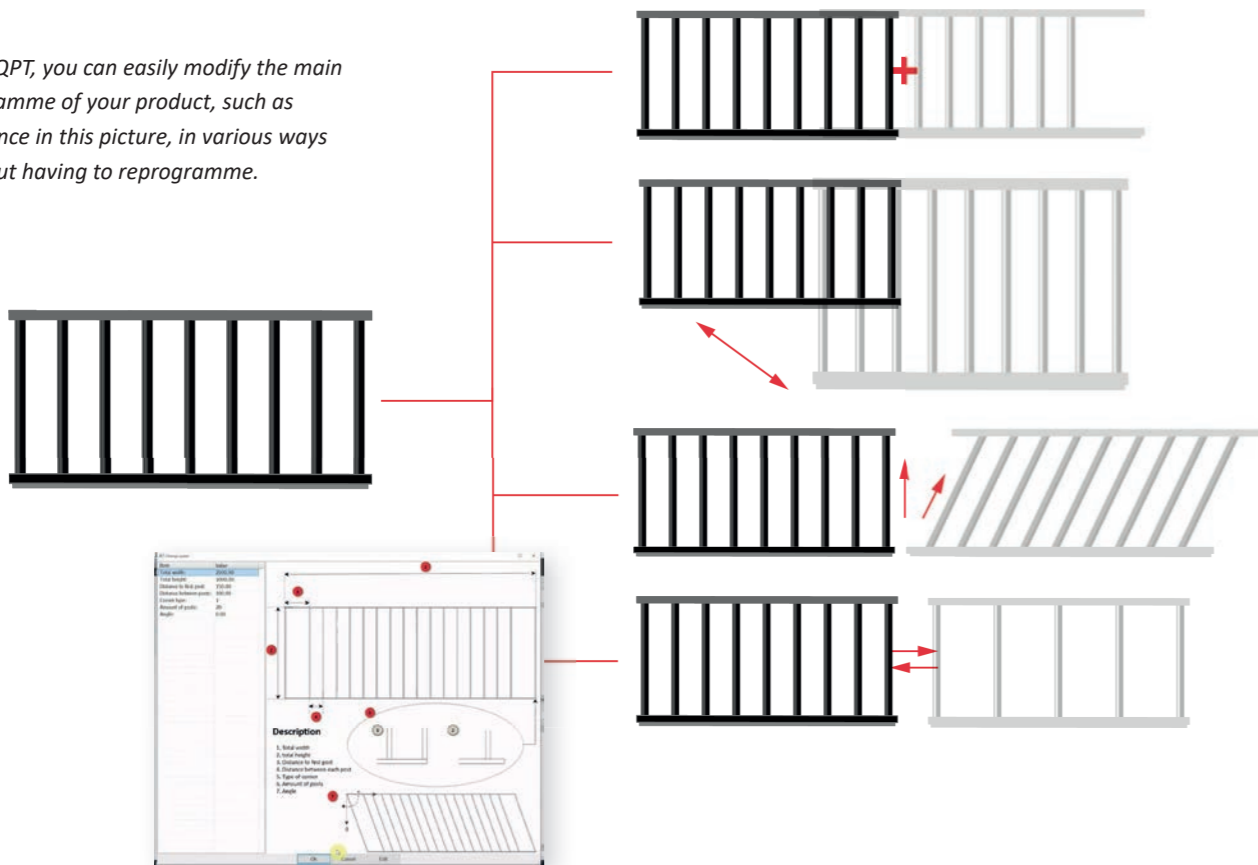
Quick Programming Tool



The software engineers at Valk Welding are constantly working on the development of tools to speed up the programming process. In addition to the standard possibilities offered by DTPS for this purpose, Valk Welding has made it possible to further speed up the programming process within product families with the help of Quick Programming Tools (QPT). In work preparation, this results in considerable time savings.

QPT is a macro module within DTPS that allows existing programming blocks to be copied, scaled, multiplied, and combined with other programming blocks. In this way, repetitive operations do not have to be programmed over and over again. Especially companies with their own products can work significantly more efficiently with this.

With QPT, you can easily modify the main programme of your product, such as the fence in this picture, in various ways without having to reprogramme.

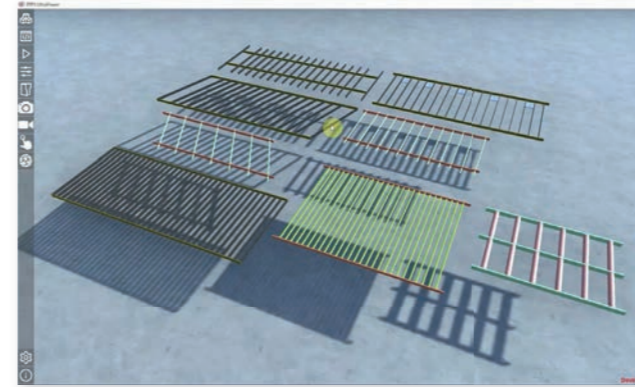


QPT in short

Using Quick Programming Tools (QPT) speeds up the programming process within product families. In work preparation, this results in significant time savings.

With an order, some data must be collected that describes the product. This data can be entered in an Excel file, or an input screen displayed in DTPS. Using QPT, it is then possible to automatically generate programs and send them to the robot. Some of the data that can be entered includes: the width and height of the product, the number of subparts, the type of subpart and the location. In this way, it is possible to go from order to production with just a few clicks.

In practice, operators work with one parent program, which defines the macros for repetitive specific operations. By applying the parent program to multiple stations, operators can enter the desired product dimensions themselves without having to reprogram the welding program. When adjustments are made to the master program, all settings such as welding parameters and torch position are automatically adjusted.



CMRS

Custom Made Robot Software

Valk Welding develops Custom Made Robot Software (CMRS solutions) to realise a fully automated welding process in addition to DTPS. CMRS is the connecting factor between different software components. CMRS integrates all software involved into one working solution. This allows us to provide and develop customized solutions for your installation. CMRS is thus a collection of software components that together perform a function that they cannot do separately. CMRS makes single-piece production on welding robots profitable.

Some application areas of CMRS are :

- Automatic generation of complete robot programs based on recipes
- Linking database systems to robot systems such as ERP and warehouse systems
- Linking to standard solutions such as DTPS, QPT, Excel, ShopFloorControl, ARP
- Controlling and integrating semi- and/or fully automatic welding jigs and robots
- Controlling and integrating specific hardware such as QR, Barcode, RF-ID and vision systems
- Controlling and integrating specific hardware such as QR, Barcode, RF-ID, and vision systems- Automating the loading

QTP library

Through years of experience, the software engineers at Valk Welding have developed a QPT macro library that can support programmers during programming. Some examples of macros are:

- Macro for importing welding tables created by Valk Welding.
- Macro for converting a welding program to a search program.
- Macro for renumbering search buffers.
- Macro for shifts not supported by DTPS
- etc.

A programmer installs the QPT library using an installer. After installation, all the available macros are ready to use.

CMRS in short

CMRS is the connecting link between different software components. CMRS integrates all the software involved into one working system.

- and unloading of the welding cell by means of Automatic Guided Vehicles (AGV).
- Developing simple human-machine interfaces to complex robotic processes
- Engineering and realisation of custom software for process/company specific robot solutions and R&D tracks
- Structure and model more complex robot automation issues together with your own engineering

CMRS saves time, increases productivity, and optimises the production process.



Valk Welding software controls 24-hour unmanned production at Meijer Metal

When employees at Meijer Metal in the Frisian town of Sint Jacobiparochie start their working day in the morning, the welding robots have been producing all through the night. Four welding robot cells there are loaded and unloaded by AGVs unmanned 24/7. In doing so, the company is building the factory of the future, in which much of the handling will be automated.

Watch the video to see this solution in practice.

Customers ERP System

Fleet Manager

AGV's



CMRS



SFC

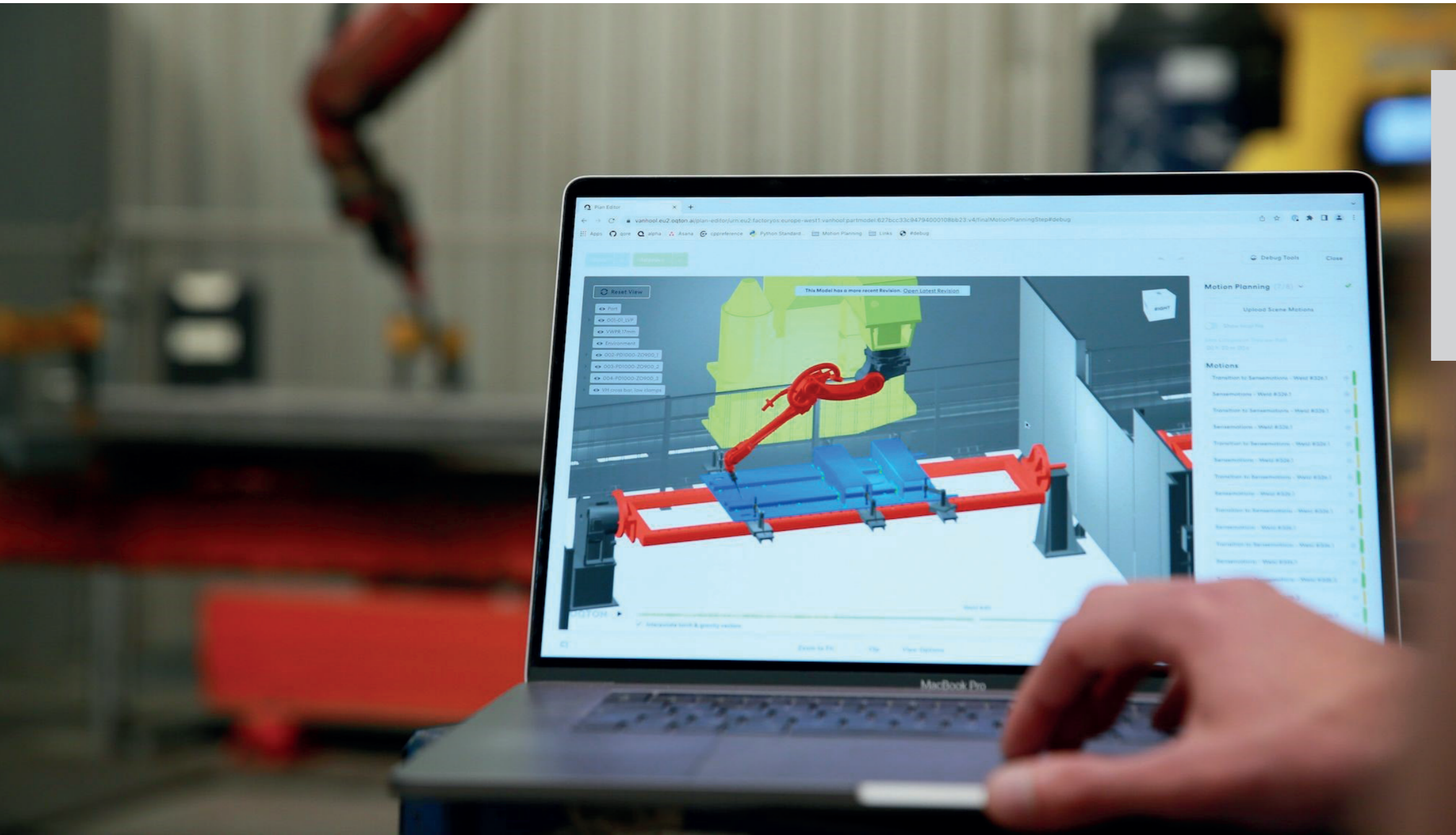


DTPS



QPT





Model Based Definition

ARP is a way for Valk Welding to keep up with developments around Model Based Definition (MBD), a way to effectively use 3D models with product data in 3D CAD software. We aim to eventually be able to extract welding information and welding parameters directly from an MBD file and thus speed up automatic robot programming.

ARP in short

ARP is software for offline programming that reduces programming time. The programs are generated and simulated automatically. After that the programs are imported into DTSP and can be sent directly to the robot for production.

ARP

Automatic Robot Programming

Automatic Robot Programming (ARP) is a collection of solutions with which we simplify the process of offline programming and speed it up to ten times. Thus, we not only dramatically increase the efficiency of this process, but we also make welding automation of single piece production attractive. This is because the ARP software automatically generates and simulates welding programs from 3D CAD files or other information sources, which also means that you do not need extensive programming knowledge.



How it works

To generate welding programs, the ARP software requires welding specifications and information about the product to be welded. Therefore, for example, you import a 3D CAD file with weld information into ARP and confirm the locations where welding is to take place. Then for each welding seam location, the software checks whether the torch and the welding part will collide and corrects these cases automatically. After this, the robot program can be generated, where the software automatically determines the start and end positions of each weld, and the touch sense points at each weld. The program is imported into DTSP and can now be sent directly to the robot for production.

Offsite Teaching in short

Offsite Teaching powered by VRPS (or Offsite Teaching) offers the ability to program a welding robot by using the already existing Virtual Reality (VR) technology for positioning the weld.



Offsite Teaching powered by VRPS

Virtual robot programming system

Offsite Teaching powered by VRPS (or Offsite Teaching) offers the possibility to program a welding robot by using the already existing Virtual Reality (VR) technique for positioning the weld.

The basic idea of Offsite Teaching is that with the handheld remote of a VR set, a movement is made that forms the basis for the welding program. This program is then perfected and executed by the robot. Offsite Teaching is therefore the first system in the market to combine the simplicity of positioning through VR with the high-end technology of an industrial welding robot and offers a unique solution within the system for accommodating inaccuracies.

Programming an industrial robot therefore becomes very easy. In addition, the work becomes lighter and cleaner. Programming products can be done very quickly, and the user only needs limited knowledge or experience in programming robots.

Because programming with the help of Offsite Teaching can

be done quickly, the use of Offsite Teaching software within production is profitable both when programming a single piece product as well as a large variety of products.

Offsite Teaching is the answer to the demand for single-piece-flow and first-time-right production.

Valk Welding has chosen to use standard VR material that is available to everyone. The only addition is the "torch head" that can be clicked into the handheld remote, and the Offsite Teaching software module.

Unique combination

Offsite Teaching powered by VRPS is the unique combination of two powerful technologies. The VRPS software is a collaborative development between Valk Welding and Panasonic. This together with the Valk Welding developments of offline programming and calibrated robotic systems form this combination. This provides a

powerful and flexible solution for easy programming of welding robots by moving a manual welding torch along the product to be welded as a manual welder does.

Industrial welding robot programming with VR Technology

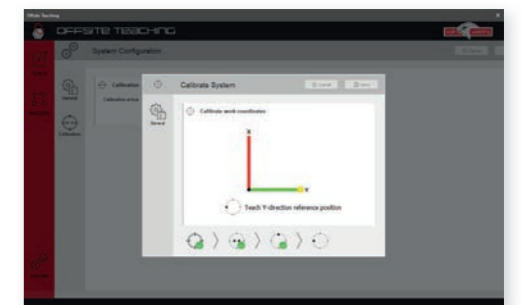
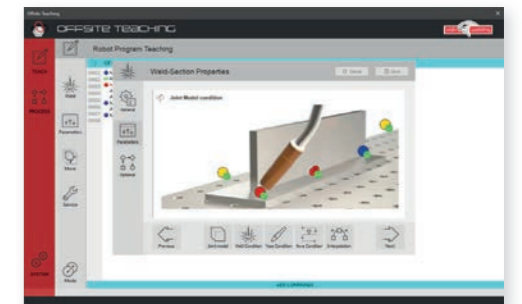
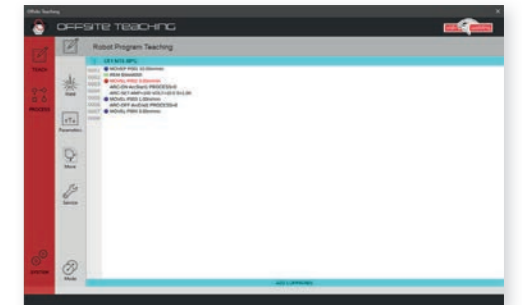
The Offsite Teaching software bridges the gap between the VR program and Panasonic's offline programming software DTPS. DTPS (Desktop Programming and Simulation Software) is a full-fledged 3D CAD/CAM system for programming and simulating the welding path on Panasonic arc welding robots.

Using the handheld remote, the VR software is used to determine the position and enter the coordinates of the various (welding) points. In the Offsite Teaching software, commands such as "welding on" and "welding off" are already given to these points. Next, the Offsite Teaching software converts the program into an offline program in the DTPS software. And finally, the DTPS software provides a usable program for the welding robot. The software guides the user through the teach process step by step in an intuitive and graphical way.

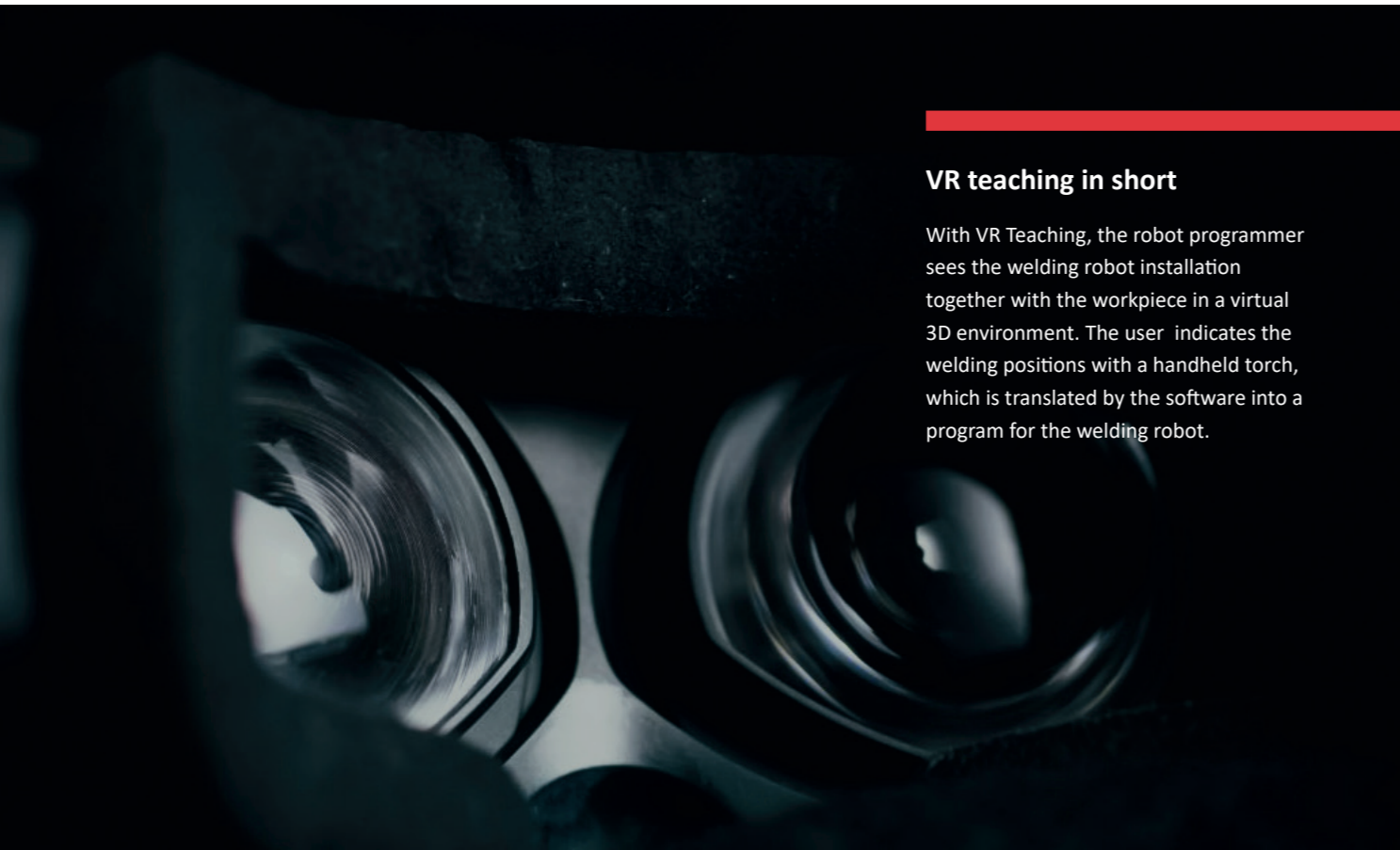
Automatically adding search movements

Positioning has the disadvantage of being inaccurate (2 to 3mm) which increases the risk of welding errors. To fully compensate for this inaccuracy, the Offsite Teaching software adds search movements to the program. Using wire searching, the robot corrects the program created up to that point. These search movements are added to the program by a macro, thus enabling the welding robot to weld the product extremely accurately.

An additional advantage of adding these search movements is that small deviations in the position of the various products are automatically caught and corrected.



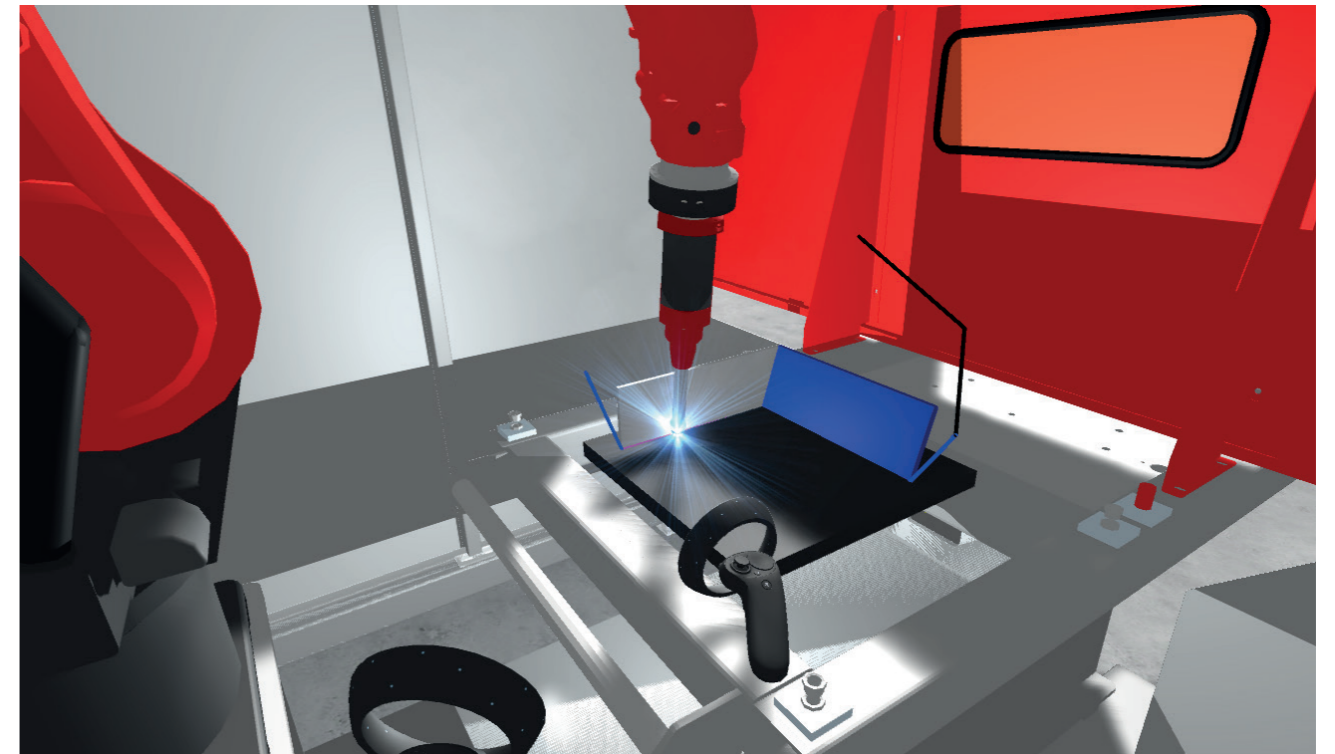
VR Teaching



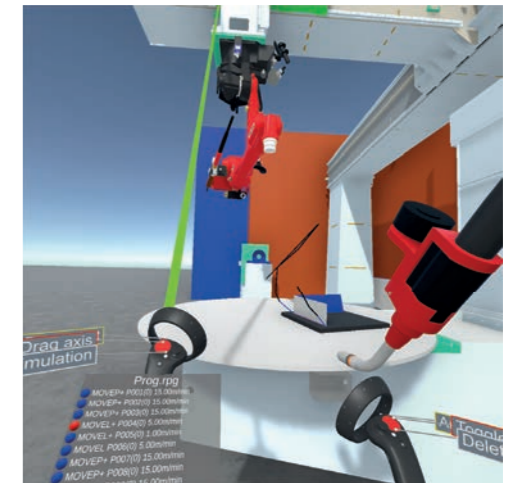
VR teaching in short

With VR Teaching, the robot programmer sees the welding robot installation together with the workpiece in a virtual 3D environment. The user indicates the welding positions with a handheld torch, which is translated by the software into a program for the welding robot.

VR Teaching bridges the gap between the popular offline programming software DTPS and the real world. The robot programmer sees the welding robot installation together with the workpiece in a virtual 3D environment. The user indicates the welding positions with a handheld torch, which is translated by the software into a program for the welding robot. This new way of programming a welding robot, also called VR Teaching, has been developed by Valk Welding as an addition to existing online, offline and Offsite Teaching methods. VR Teaching offers additional value compared to programming from behind your screen (offline), because use of the new technology gives more insight into the workpiece. VR Teaching is fully integrated with DTPS.

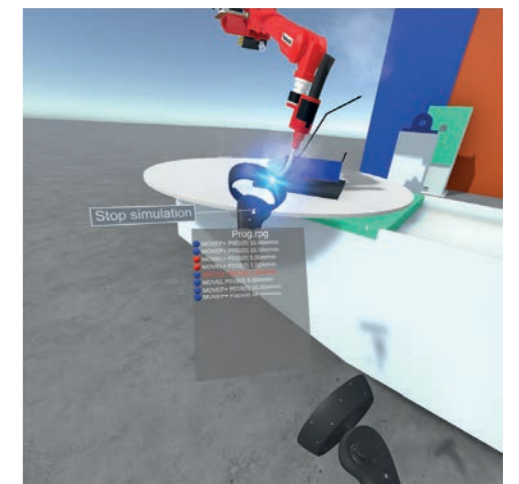


When programming offline with DTPS on the PC, the programmer sees the welding robot installation and the workpiece in a flat view of the 3D model on the screen. Virtual Reality, on the other hand, allows you to see the same environment in 3D with depth. Because sensors follow the movements of your head, the VR environment moves in the same way. In the virtual world, it is easier and faster than in DTPS to zoom in on details and in simulation mode to perform better visual inspections. There is more insight into the workpiece than from behind a screen. What programmers are used to in offline programming behind the computer, they can now do virtually but faster, simpler, and more intuitively. Moreover, with the VR glasses you do not have to stand in the production situation.



With this technology a big step has been made in transferring the years of knowledge the professionals have to a digital world with the conveniences of offline programming. Welders with the precise knowledge about torch positions and welding movements can effortlessly use this in the new technology.

VR Teaching can also be used for other applications such as the virtual testing of jigs for accessibility to the robot torch, but also for the ergonomic insertion of parts, opening and closing of clamps, etc. It also provides quick insight into cycle times and can be used to present future installations to new customers.



SFC

Shop Floor Control

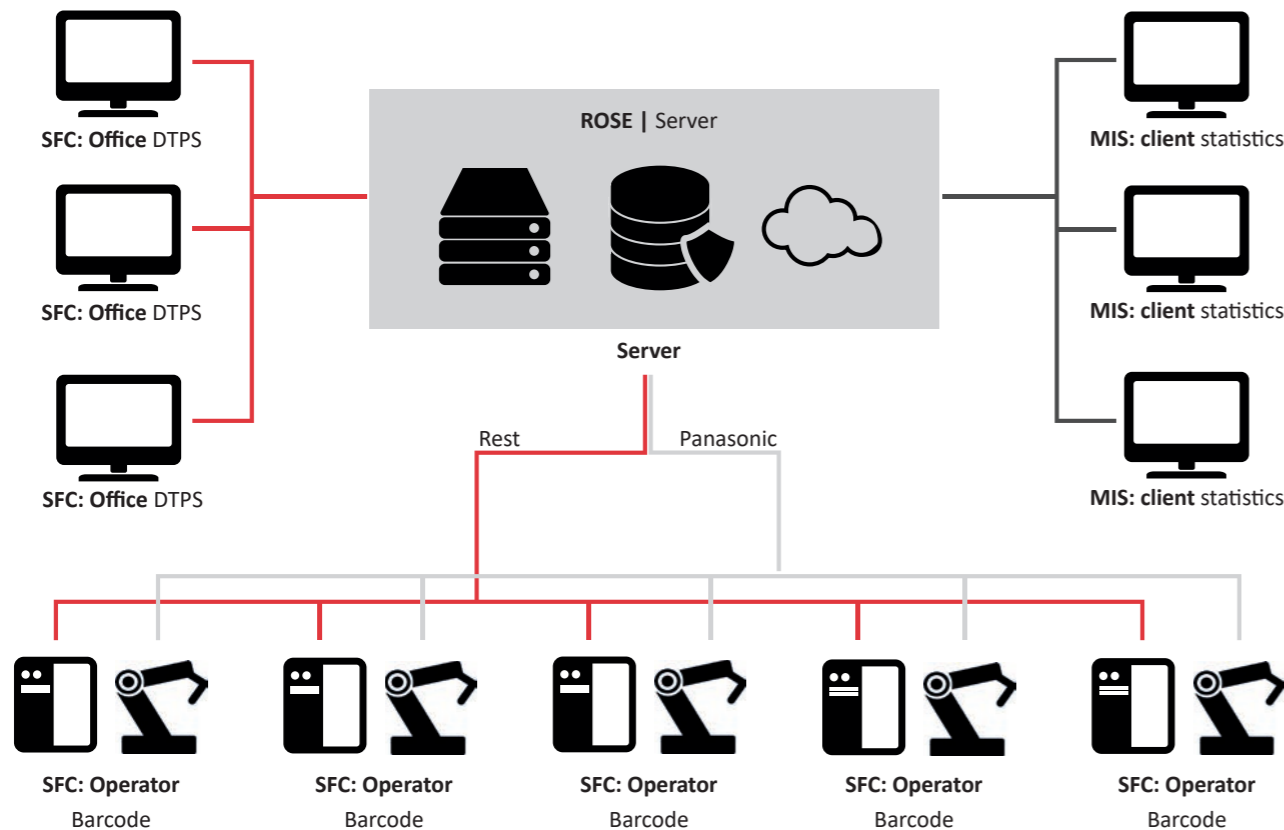
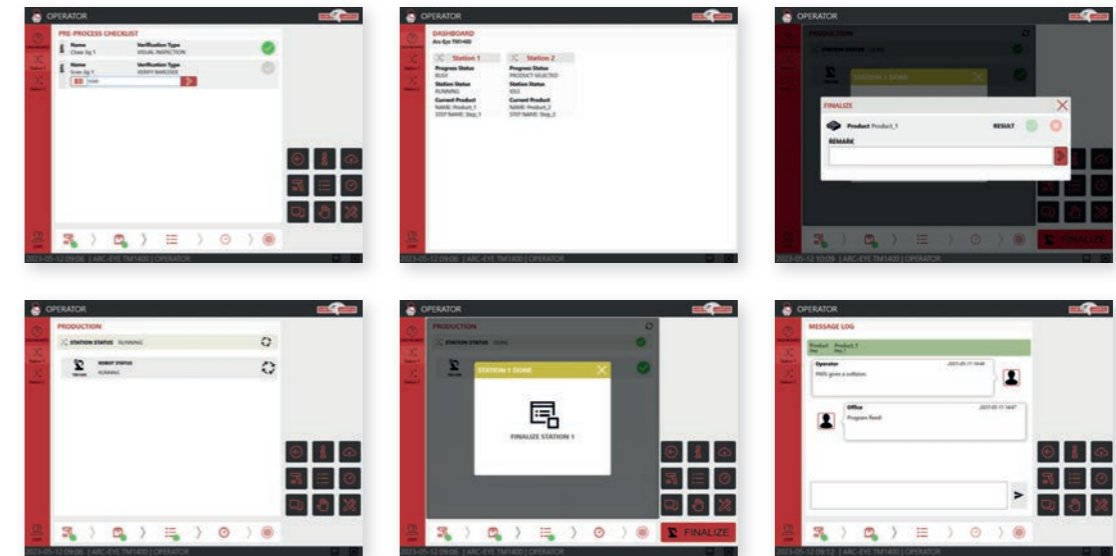


Shop Floor Control, or SFC, is an application to automate, structure and manage the office and workshop environment of the robotic welding process. SFC automates from planning to operator instructions. The platform makes use of the ability of the Panasonic robots to retrieve and send live data. SFC is certainly a valuable addition for companies with multiple workstations or welding robot installations.

SFC ensures clear and transparent communication within the company. Production can be fed through barcodes or pre-planned products to be produced. The operator then uses the barcode or scheduled production batch to automatically provide the robot installation with the correct and most recent set of robot programs. By using a chat function any improvements can be passed on to the programmer. These chats are automatically linked to the production in question. This means that the programmer does not always have to be present on site. Everything is transparent, time-bound and recorded in the correct context.

SFC in short

Shop Floor Control or SFC, is an application to automate, structure and manage the office and shop floor environment of the robotic welding process. From planning to operator instructions.



The platform consists of 3 distinct components, the SFC: Server, the SFC: Office and the SFC: Operator.

- SFC: server runs on your server and is responsible for the communication between the robots and the different components. The server provides a central network location for your robot data and the version management of your programs and robot installations.
- SFC: Office can be used by all your DTPS computers on the network to prepare work including programs for the robots on your shop floor and beyond. The ability to group similar robot installations allows you to program generically and easily test and schedule your programs for multiple robots at the same time. The SFC: Office software converts and verifies your programs using DTPS-macros and offers a large amount of flexibility.
- SFC: Operator runs on a computer at each robot installation and forms the control panel of your production process. The operator can select the product by means of the (bar) code and send the right robot programs to the robot.

The production can also be split into multiple phases, for each step in the process verification actions can be added. For example, at the start of the production step the operator must first scan a barcode on the jig or perform a visual check and fill in the checklist. To further support the operator in production, documents or web pages can be linked to the production step. This makes it possible, for example, to offer work drawings or work instructions.

To keep the line between the workshop and the office short, there is a built-in messaging system. The messages are automatically linked to the product and the phase. The messages arrive at the SFC application and are automatically linked to the product and the phase. This is an effective method for communicating comments.

In short, SFC provides these 3 pillars:

A managed factory control:

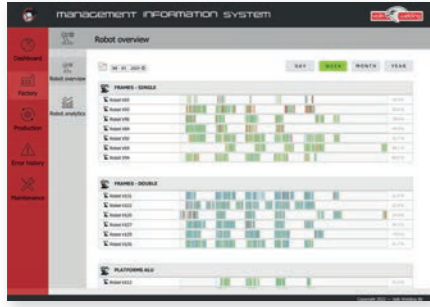
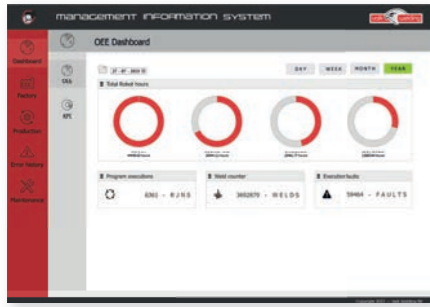
- Simple grouping of similar robot installations.
- Generic programming at group level.
- Automatic program conversion and verification between group members.
- Version control for installation definitions and robot programming.

A structured workflow:

- Barcode for product selection and verification
- Phasing of production.
- Checklists and feedback verification.
- Direct communication log between operator and programmer environment.

Automation of the process:

- The desktop environment prepares the programs, books them and links them to a barcode.
- The shop floor environment scans the barcode, performs the checks, and starts the process.
- SFC provides direct communication with the robot, keeps track of the entire process, and ensures that the right programs automatically enter the robot.



MIS

Management Information System

The Management Information System (MIS) is a software program developed by Valk Welding in which companies have full real-time insight into what is happening with the robotic installations that are in production. From a PC, mobile or a tablet, in production or on the road.

Companies with multiple welding robots in use want more and more insight and control at the management level on both performance, process progress, maintenance and welding data. This data is needed to make timely adjustments to the process and increase efficiency, and is needed to record welding quality for each product. The second generation of the Management Information System (MIS) that Valk Welding has developed for this purpose provides the solution.

The main reason for Valk Welding to further develop the Management Information System (MIS) is that the number of customers with multiple welding robots in use, has risen sharply. In line with this, the need for more control over production has also increased.

- When and for how long is a robot at a standstill?
- What is the reason for the downtime?
- How high is the robot's duty cycle time?
- Do the cycle times match the time study?
- Can I collect and record welding data?

These are all data that the production management wants to be able to manage. The ability to collect and record all welding data also offers a solution in terms of product liability.

MIS runs on ROSE (Robot Object Server), on which the Valk Welding Shop Floor Control (SFC) solution also runs.

Realtime data from the server

The data from the robot controls is transmitted in real time to the central server, enabling monitoring, data analysis, traceability and data logging. MIS visualizes this information in the form of graphs and tables. Valk Welding has developed several widgets that allow companies to put together their own dashboard, specifically tailored to the company's needs.

Monitoring

Companies receive a dashboard with a complete overview of annual totals across all systems. These annual totals include the number of hours, turn-on time, welding hours, number of programs processed, welding wire consumption, and so on.

Robot Analysis

- A complete and up-to-date overview of Key Performance Indicators (KPIs) for each individual welding robot system.
- A detailed overview per period.
- Daily insight into log data including any deviations that may have occurred.
- Detailed analysis options.

Product traceability

All data can be retrieved at product level and over a specific period. Based on this data, the product can be checked before it goes to the next step in the production process. A data log is recorded for each product. The datalog includes a series of welding data in chronological order.

Service management

MIS provides insight into the condition of the installation so that companies can perform preventive and timely maintenance. For example, consider the amount of pressure that is on each axis of a robot. In this way, it becomes clear which axis requires preventive maintenance.

Support by Valk Welding

MIS has been fully developed in-house by Valk Welding and is therefore directly supported by Valk Welding.

ROSE

Robot Object Server

ROSE is the name of the service on which SFC (Shop Floor Control) and MIS (Management Information System) can be switched on. MIS and SFC can be used separately or simultaneously. This depends on the wishes of the customer.

For more information about SFC, see the following pages.

MIS in short

MIS is a program in which a company can have real time, full insight, into what happens with robot installations that are in production. Viewable from a PC, mobile phone or tablet, at the facility or on the road.



Watch our video

Valk Welding Partner Zone:

a complete platform for your software

In order to serve customers with software from Valk Welding better and faster now and in the future, Valk Welding presents the Partner Zone. This online communication platform provides access to all information about our software solutions, including DTPS, QPT, ARC-EYE laser tracking camera with Adaptive Welding, MIS and SFC.

Updates and libraries

The Partner Zone was created to provide customers with even better service. Targeted access allows each customer to quickly access the right information. For example, MIS users will find the latest widgets, DTPS'ers with a support contract will download tools that allow them to program more efficiently, and customers with a laser vision system will find the latest information on the ARC-EYE. The Partner zone provides one place where customers can find all the important software and documentation.



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